

Prefixes

a=10⁻¹⁸, f=10⁻¹⁵, p=10⁻¹², n=10⁻⁹, μ = 10⁻⁶, m=10⁻³, c=10⁻², k=10³, M=10⁶, G=10⁹, T=10¹², P=10¹⁵.
 atto, femto, pico, nano, micro, milli, centi, kilo, mega, giga, tera, peta.

Physical Constants

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| $g = 9.80 \text{ m/s}^2$ (gravitational acceleration) | $G = 6.67 \times 10^{-11} \text{ N}\cdot\text{m}^2/\text{kg}^2$ (Gravitational constant) |
| $M_E = 5.98 \times 10^{24} \text{ kg}$ (mass of Earth) | $R_E = 6380 \text{ km}$ (mean radius of Earth) |
| $m_e = 9.11 \times 10^{-31} \text{ kg}$ (electron mass) | $m_p = 1.67 \times 10^{-27} \text{ kg}$ (proton mass) |
| $c = 299792458 \text{ m/s}$ (exact speed of light) | $\sigma = 5.67 \times 10^{-8} \text{ W/m}^2\cdot\text{K}^4$ (Stefan-Boltzmann constant) |
| $u = 1.6605 \times 10^{-27} \text{ kg}$ (atomic mass unit) | $N_A = 6.022 \times 10^{23}/\text{mol}$ (Avogadro's number) |
| $R = 8.314 \text{ J/mol}\cdot\text{K}$ (gas constant) | $k = 1.38 \times 10^{-23} \text{ J/K}$ (Boltzmann's constant) |

Units and Conversions

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| 1 inch = 1 in = 2.54 cm | 1 foot = 1 ft = 12 in = 0.3048 m | |
| 1 mile = 5280 ft = 1760 yards | 1 mile = 1609.344 m = 1.609344 km | |
| 1 m/s = 3.6 km/hour | 88 ft/s = 60 mile/hour | 1 m ³ = 1000 L |
| 1 acre = (1 mile) ² /640 = 43 560 ft ² | 1 hectare = (100 m) ² = 10 ⁴ m ² | 1 cal = 4.186 J |
| 1 lb = 4.45 N | 1 N = 0.225 lb | 1 J = 1 joule = 1 N·m |

| symbol | element | atomic number | mass number |
|--------|----------|---------------|-------------|
| H | hydrogen | 1 | 1.00794 |
| He | helium | 2 | 4.00260 |
| C | carbon | 6 | 12.0107 |
| N | nitrogen | 7 | 14.0067 |
| O | oxygen | 8 | 15.9994 |
| Ne | neon | 10 | 20.180 |
| Ar | argon | 18 | 39.948 |
| Fe | iron | 26 | 55.845 |
| Ni | nickel | 28 | 58.693 |
| Cu | copper | 29 | 63.546 |
| Au | gold | 79 | 196.97 |
| U | uranium | 92 | 238.03 |

Mass numbers are atomic masses in units of “u” where 1 u = 1.6605 × 10⁻²⁷ kg, or, molar masses for the element (1 mole = 6.02 × 10²³ atoms), measured in grams/mole. ($N_A \times 1 \text{ u} = 1 \text{ gram}$)

Algebra, Geometry, Trigonometry

Quadratic equations: $ax^2 + bx + c = 0$, solved by $x = (-b \pm \sqrt{b^2 - 4ac}) / (2a)$.
 Triangles: $A = \frac{1}{2}bh$, Circles; $C = 2\pi r$, $A = \pi r^2$, arc = $s = r\theta$. Spheres: $A = 4\pi r^2$, $V = \frac{4}{3}\pi r^3$.
 $\sin \theta = (\text{opp})/(\text{hyp})$, $\cos \theta = (\text{adj})/(\text{hyp})$, $\tan \theta = (\text{opp})/(\text{adj})$, $(\text{opp})^2 + (\text{adj})^2 = (\text{hyp})^2$.
 $\sin \theta = \sin(180^\circ - \theta)$, $\cos \theta = \cos(-\theta)$, $\tan \theta = \tan(180^\circ + \theta)$, $\sin^2 \theta + \cos^2 \theta = 1$.

OpenStax Ch 1: Units, measurements, errors or uncertainties

Unit conversions: value = # (old units), (old units) × ($\frac{\text{new units}}{\text{old units}}$) = (new units).
 Percent error: measurement = value ± error, percent error = (error / value) × 100%.

OpenStax Ch 2: 1D Kinematics - Straight-line motion

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| Velocity: | $\bar{v} = \Delta x / \Delta t$ | $\Delta x = x - x_0$ | $v(t) = \text{slope of } x(t)$ |
| Acceleration: | $\bar{a} = \Delta v / \Delta t$ | $\Delta v = v - v_0$ | $a(t) = \text{slope of } v(t)$ |
| Constant acceleration: | $v = v_0 + at$, $x = x_0 + v_0t + \frac{1}{2}at^2$, | $\bar{v} = \frac{1}{2}(v_0 + v)$, $x = x_0 + v_{\text{avg}}t$, | $\Delta x = \bar{v}\Delta t$. $v^2 = v_0^2 + 2a\Delta x$. |
| Free fall (+y-axis is up): | $y = y_0 + v_{0y}t - \frac{1}{2}gt^2$, | $v_y = v_{0y} - gt$, | $v_y^2 = v_{0y}^2 - 2g\Delta y$. |

OpenStax Ch 3: Vectors & 2D & 3D Motion

Vector $\mathbf{V} = \vec{V} = (V_x, V_y)$, magnitude = $V = \sqrt{V_x^2 + V_y^2}$, direction = $\theta = \tan^{-1}(V_y/V_x)$.
 $\theta = \text{angle from } x\text{-axis to } \mathbf{V}$, $V_x = V \cos \theta$, $V_y = V \sin \theta$.
 Addition: $\mathbf{A} + \mathbf{B}$, head to tail, Subtraction: $\mathbf{A} - \mathbf{B}$ is $\mathbf{A} + (-\mathbf{B})$, $-\mathbf{B}$ is \mathbf{B} reversed.

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| Projectiles: | $a_x = 0,$ $a_y = -g,$ | $v_x = v_{0x},$ $v_y = v_{0y} - gt,$ | $x = x_0 + v_{0x}t,$ $y = y_0 + v_{0y}t - \frac{1}{2}gt^2,$ | (horizontal x -axis), (upward y -axis). | $R = (v_0^2/g) \sin 2\theta_0.$ |
| Relative Motion: | $\mathbf{V}_{BS} = \mathbf{V}_{BW} + \mathbf{V}_{WS},$ | Boat, Shore, Water. | BS = "boat relative to shore", etc. | | |

OpenStax Ch 4: Newton's Laws

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| Newton's 1 st Law: | $\vec{a} = \frac{\Delta\vec{v}}{\Delta t} = 0$ unless $\vec{F}_{\text{net}} \neq 0,$ | $\vec{F}_{\text{net}} = \sum \vec{F}_i =$ sum of all forces on a mass. |
| Newton's 2 nd Law: | $\vec{F}_{\text{net}} = m\vec{a},$ | $F_{\text{net},x} = ma_x, F_{\text{net},y} = ma_y, F_{\text{net},z} = ma_z.$ |
| Newton's 3 rd Law: | $\vec{F}_{AB} = -\vec{F}_{BA},$ | Forces exist in action-reaction pairs. |
| Gravitational force near Earth: | $F_G = mg,$ downward. | Apparent weight is force measured by a scales. |
| Gravity components on inclines: | $F_{\parallel} = mg \sin \theta, F_{\perp} = mg \cos \theta,$ | \leftarrow for incline at angle θ to horizontal. |
| Spring force: | $F_s = -kx,$ | x is the displacement from equilibrium. |

OpenStax Ch 5: Friction

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| Normal force: | N or $F_N,$ | acts perpendicular to a surface, acts on the object. |
| Static friction (object is stuck): | $f_s \leq \mu_s N,$ | Can balance other forces in any direction. |
| Kinetic friction (object sliding): | $f_k = \mu_k N,$ | Acts against the relative motion of surfaces. |

OpenStax Ch 6: Circular Motion

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| Centripetal Acceleration: | $a_c = v^2/r = \omega^2 r,$ | towards the center of the circle, | Use ω in rad/sec! |
| Circular motion: | speed $v = 2\pi r/T,$ speed $v = \omega r,$ | frequency $f = 1/T,$ angular speed $\omega = 2\pi f = 2\pi/T,$ | T = period of one revolution. ω is in rad/sec. |
| Gravitation: | $F = Gm_1m_2/r^2,$ | free fall $g = GM/r^2,$ | $G = 6.67 \times 10^{-11} \text{ Nm}^2/\text{kg}^2.$ |
| Orbits: | $v^2/r = g = GM/r^2;$ | speed $v = \sqrt{GM/r},$ | centripetal $a_c =$ free fall $g.$ |

OpenStax Ch 7: Work & Energy

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| Forces: | $F_x,$ | $F_{\text{gravity},y} = -mg,$ | $F_{\text{spring}} = -kx.$ |
| Work: | $W = F_x \Delta x \cos \theta,$ | $W_{\text{gravity},y} = -mg\Delta y,$ | $W_{\text{spring}} = -\frac{1}{2}k(x_f^2 - x_i^2).$ |
| PE: | $\Delta PE = -W_{\text{force}},$ | $PE_{\text{gravity}} = mgy,$ | $PE_{\text{spring}} = \frac{1}{2}kx^2.$ |
| KE: | $KE = \frac{1}{2}mv^2,$ | $\Delta KE = W_{\text{net}},$ | $W_{\text{net}} =$ work of all forces. |
| Conservation of Energy: | $\Delta KE + \Delta PE = W_{\text{NC}},$ | NC = non-conservative forces. | |
| Power: | $P_{\text{ave}} = W/t,$ | or use $P_{\text{ave}} =$ energy/time. | |

OpenStax Ch 8: Momentum

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| Linear momentum: | $\vec{p} = m\vec{v},$ | impulse $\Delta\vec{p} = m\Delta\vec{v} = \vec{F}_{\text{ave}} \Delta t.$ |
| Conservation of Momentum: | $m_A\vec{v}_A + m_B\vec{v}_B = m_A\vec{v}'_A + m_B\vec{v}'_B,$ | (2-body collisions, $\vec{F}_{\text{net}} = 0).$ |
| 1D elastic collision: | $\frac{1}{2}m_A v_A^2 + \frac{1}{2}m_B v_B^2 = \frac{1}{2}m_A v_A'^2 + \frac{1}{2}m_B v_B'^2,$ | or $v_A - v_B = -(v'_A - v'_B).$ |

OpenStax Ch 9: Rotational Motion

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| Coordinates: | 1 rev = 2π rad, | 1 rev = $360^\circ,$ | $\omega = 2\pi f,$ | $f = \frac{1}{T}.$ |
| Averages: | $\bar{\omega} = \frac{\Delta\theta}{\Delta t},$ | $\Delta\theta = \bar{\omega}\Delta t,$ | $\bar{\alpha} = \frac{\Delta\omega}{\Delta t},$ | $\Delta\omega = \bar{\alpha}\Delta t.$ |
| Linear vs. angular: | $l = \theta r,$ | $v = \omega r,$ | $a_{\text{tan}} = \alpha r,$ | $a_c = \omega^2 r,$ use radians! |
| Constant acceleration: | $\omega = \omega_0 + \alpha t,$ | $\theta = \theta_0 + \omega_0 t + \frac{1}{2}\alpha t^2,$ | $\bar{\omega} = \frac{1}{2}(\omega_0 + \omega),$ | $\omega^2 = \omega_0^2 + 2\alpha\Delta\theta.$ |
| Torque, Dynamics: | $\tau = rF \sin \theta,$ | $I = \Sigma mr^2,$ | $\tau_{\text{net}} = I\alpha.$ | |
| Rotational Inertias: | $I = MR^2,$ | $I = \frac{1}{2}MR^2,$ | $I = \frac{2}{5}MR^2,$ | $I = \frac{1}{12}ML^2.$ |
| (about centers) | (hoop) | (solid cylinder) | (sphere) | (thin rod) |
| KE, A. Momentum: | $KE_{\text{rot}} = \frac{1}{2}I\omega^2,$ | $L = I\omega,$ | $\Delta L = \tau_{\text{net}}\Delta t.$ | |
| Work, power: | $W = \bar{\tau}\Delta\theta,$ | $P = \tau\omega.$ | | |

OpenStax Ch 10: Static Equilibrium

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| $\Sigma F_x = \Sigma F_y = \Sigma F_z = 0,$ | $\Sigma \tau = 0,$ | $\tau = rF \sin \theta = r_{\perp}F = rF_{\perp},$ | $\tau =$ torque around a chosen axis. |
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OpenStax Ch 11: Static Fluids

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| 1 atmosphere = 1 atm = 101.3 kPa = 1.013 bar = 760 torr = 760 mm Hg = 14.7 lb/in ² . |
| Units: 1 Pa = 1 N/m ² , 1 bar = 10 ⁵ Pa, 1 mm Hg = 133.3 Pa. |
| Density: $\rho = m/V$, $\rho_{\text{H}_2\text{O}} = 10^3 \text{ kg/m}^3$ (4°C), $10^3 \text{ kg/m}^3 = 1 \text{ g/cm}^3$. |
| Pressure: $P = F/A$, $P_2 = P_1 + \rho g d$, $P_{\text{abs}} = P_{\text{atm}} + P_{\text{gauge}}$. |
| Archimedes: $F_B = \rho_{\text{fluid}} g V_s$, $F_B = \text{weight of displaced fluid}$. |

OpenStax Ch 12: Fluid Dynamics

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| Moving fluid: $Q = Av = \text{constant}$, Bernoulli Eqn: $P + \frac{1}{2}\rho v^2 + \rho g y = \text{constant}$. |
| Viscosity: Definition: $F = \eta Av/\ell$, Poiseuille Eqn: $Q = \pi r^4(P_2 - P_1)/(8\eta L)$. |

OpenStax Ch 16: Oscillations and Waves

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| Oscillators: $F = -kx = ma$, $f = 1/T$, $\omega = 2\pi f = 2\pi/T$, $\omega = \sqrt{k/m}$, $\omega = \sqrt{g/L}$. |
| Energy, speed: $E = \frac{1}{2}mv^2 + \frac{1}{2}kx^2$, $E = \frac{1}{2}kA^2 = \frac{1}{2}mv_{\text{max}}^2$, $v_{\text{max}} = \omega A$. |
| Waves: $\lambda = vT$, $v = f\lambda$, $I = P/A$, $I = P/4\pi r^2$. |
| Wave speed: $v = \sqrt{F_T/(m/L)}$ (strings), $v = (331 \text{ m/s})\sqrt{T/(273 \text{ K})}$ (sound in air). |
| Standing waves: node to node = $\lambda/2$, sketch displacement of string or molecules. |
| nodes at both ends of strings. nodes (antinodes) at closed (open) ends of pipes. |

OpenStax Ch 17: Sound

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| Sound in air: $v = (331 \text{ m/s})\sqrt{T/273 \text{ K}}$, $v = 343 \text{ m/s}$ at 20°C, $d = vt$, $I = P/A$. |
| Sound level: $\beta = (10 \text{ dB}) \log(I/I_0)$, $I = I_0 10^{\beta/(10 \text{ dB})}$, $I_0 = 10^{-12} \text{ W/m}^2$. |

OpenStax Ch 13: Ideal Gases & Kinetic Theory

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| Moles: $n = N/N_A$, $n = M/M_A$, $M = \text{sample mass}$. |
| Avogadro number: $N_A = 6.022 \times 10^{23}/\text{mol}$, $1 \text{ u} = (1 \text{ gram})/N_A$, $1 \text{ u} = 1.6605 \times 10^{-27} \text{ kg}$. |
| Temperature scales: $T(^{\circ}\text{C}) = \frac{5}{9}[T(^{\circ}\text{F}) - 32]$, $T(^{\circ}\text{F}) = \frac{9}{5}T(^{\circ}\text{C}) + 32$, $T(\text{K}) = T(^{\circ}\text{C}) + 273.15$. |
| Thermal expansion: $\Delta L = \alpha L_0 \Delta T$, $\Delta V = \beta V_0 \Delta T$. |
| Ideal Gas Law: $PV = nRT = Nk_B T$, $R = 8.314 \text{ J/mol}\cdot\text{K}$, $k_B = R/N_A = 1.38 \times 10^{-23} \text{ J/K}$. |
| Kinetic Theory: $\overline{\text{KE}} = \frac{1}{2}mv_{\text{rms}}^2 = \frac{3}{2}k_B T$, $v_{\text{rms}} = \sqrt{3k_B T/m} = \sqrt{3RT/M_A}$, $m = M_A/N_A = \text{atom or molecule}$. |

OpenStax Ch 14: Heat Transfer

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| Heat units: 1.00 cal = 4.186 J, 1.00 Cal = 1.00 kcal = 4186 J. |
| Internal Energy: $U = \frac{3}{2}NkT = \frac{3}{2}nRT$, \leftarrow (ideal monatomic gases). |
| Heats absorbed: $Q = mc\Delta T$ ($c = \text{specific heat}$), $Q = mL$ ($L_F = \text{fusion}$, $L_V = \text{vaporization}$). |
| For water: $c_{\text{liq}} = 1.00 \text{ cal}/(\text{g}\cdot\text{C}^{\circ}) = 4.186 \text{ kJ}/(\text{kg}\cdot\text{C}^{\circ})$, $c_{\text{ice}} = 0.50 \text{ cal}/(\text{g}\cdot\text{C}^{\circ}) = 2.1 \text{ kJ}/(\text{kg}\cdot\text{C}^{\circ})$. |
| $L_F = 79.7 \text{ kcal/kg} = 333 \text{ kJ/kg}$, $L_V = 539 \text{ kcal/kg} = 2260 \text{ kJ/kg}$. |
| Heat transfer: Conduction: $P = \frac{\Delta Q}{\Delta t} = kA \frac{\Delta T}{l}$, Radiation: $P_{\text{net}} = \frac{\Delta Q}{\Delta t} = e\sigma A(T_1^4 - T_2^4)$. |
| Solar Energy: $P = \frac{\Delta Q}{\Delta t} \approx (1000 \text{ W/m}^2) eA \cos \theta$, $\sigma = 5.67 \times 10^{-8} \text{ W/m}^2 \cdot \text{K}^4$. |

OpenStax Ch 15: The Laws of Thermodynamics

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| Process (const): isobaric (P), isothermal (T), isochoric (V), adiabatic ($Q = 0$). |
| 1 st Law: $\Delta U = Q - W$, $W = \text{area under } P(V)$, $W = P\Delta V$ for isobaric. |
| Heat Engines: $W = Q_H - Q_L$, $e = \frac{W}{Q_H} = 1 - \frac{Q_L}{Q_H}$ |
| AC, Heat Pumps: $W = Q_H - Q_L$, AC: $\text{COP} = \frac{Q_L}{W}$, heat pumps: $\text{COP} = \frac{Q_H}{W}$. |
| Power: $P_{\text{ave}} = W/t$, or use $P_{\text{ave}} = \frac{\text{energy}}{\text{time}}$, $\frac{Q_L}{Q_H} = \frac{T_L}{T_H}$ for Carnot cycle. |
| 2 nd Law, Entropy: $\Delta S_{\text{total}} \geq 0$, $\Delta S_{\text{reversible}} = 0$, $\Delta S_{\text{system}} = Q/T_{\text{ave}}$. |